IN THE SPECIFICATION:

Please amend paragraph [0025] as follows:

First, a left half of the handle 18 is discussed. A portion of the handle 18 extending from a fixing point PL1 on a left side of the handle holder 19 has a mass of mL1 (hereinafter referred to as "left handle mass mL1"), while the left grip 20 has a mass of mL2 (hereinafter referred to as "left grip mass mL2"). Thus, the left side has a mass of mL3 which is a sum of the left handle mass mL2 and the left grip mass mL2 (mL3 = mL1 + mL2). The sum mL3 of the left side has a center of gravity as at GL. The present invention is characterized in that the left grip 20 is mounted to the handle 19 by a screw 24 at only a single mounting portion 25 (see Figs. 5A and 5B) substantially at its center of gravity GL corresponding to ~~the sum of~~ the left side mass mL3 which is a sum of the left handle portion mass mL1 and the left grip mass mL2, or at a position proximate thereto.

Please amend paragraph [0026] as follows:

Now, a right half of the handle 18 is discussed. A portion of the handle 18 extending from a fixing point PR1 on a right side of the handle holder 19 has a mass of mR1 (hereinafter referred to as "right handle mass mR1"), while

the right grip 39 has a mass of mR2 (hereinafter referred to as "right grip mass mR2"). Thus, the right side has a mass of mR3 which is a sum of the right handle mass mR1 and the right grip mass mR2 (mR3 = mR1 + mR2). The sum mR3 of the right side has a center of gravity as at GR. The present invention is characterized in that the right grip 30 is mounted to the handle 18 by a screw 24 at only a single mounting portion 25 substantially at its center of gravity GR corresponding to ~~the sum of~~ the right side mass mR3 which is a sum of the right handle portion mass mR1 and the right grip mass mR2, or at a position proximate thereto.